



Limits & Differentiation Rules (Units 1-3)

Limit Foundations
Limit: lim_{x-a} f(x) = L iff for all epsilon > 0, exists delta > 0 s.t. 0 < |x-a| < delta -> |f(x) - L| < epsilon.
Continuity at x = a: lim_{x-a} f(x) = f(a). Check: defn, left/right limits match & exist.
IVT: f cts. on [a,b] & k b/w f(a), f(b) -> exists c in (a,b) where f(c) = k. Use on MC to prove zeros, critical pts.
Jump disc. (left != right limit); removable (hole, not value); infinite (vert. asymptote).

Derivative Rules & Strategies

Power, sum, const. mult. (on sheet). Product rule: (uv)' = u'v + uv'. Chain: (f o g)' = f'(g) * g'.
Quotient: (u/v)' = (u'v - uv')/v^2. When to use: quotient rule slower than rewriting as u*v^-1.
Implicit diff.: diff. both sides wrt x, collect dy/dx terms, solve. Use when y not explicit or relation is implicit.
Inverse fn.: (f^-1)'(x) = 1/f'(f^-1(x)). Check: f'(f^-1(a)) in denominator.
Log diff.: ln both sides, diff., solve y'. Use on products/quotients of many terms.

Table with 2 columns: Derivative, Rule. Rows include e^u, ln|u|, sin u, cos u, tan u, a^u.

Common Traps

Chain rule: (sin 2x)' = 2 cos 2x, not cos 2x. Always include inner deriv.
Implicit: solve for dy/dx algebraically. Never leave dy/dx on both sides.

Applications of Differentiation (Units 4-5)

Optimization & Shape
MVT: f cts. on [a,b], diff. on (a,b) -> exists c where f'(c) = [f(b) - f(a)] / (b - a). Use to justify crit. pts.
Crit. pt. test: f'(x) = 0 or undef. 1st deriv. test: sign of f' before/after -> max/min. 2nd deriv. test: f''(c) < 0 -> max; > 0 -> min.
Concavity: f''(x) > 0 -> concave up; f''(x) < 0 -> concave down. Inflection pt.: f'' changes sign.
Optimization: set up constraint, express obj. fn. in 1 var., find crit. pts., test endpoints & crit. pts.
Related rates: diff. constraint wrt time, substitute known rates, solve for unknown rate. Draw & label diagram.

Behavior & Asymptotes

Horiz. asymptote: check lim_{x-to+/-inf} f(x). Vert. asymptote: f' -> +/-inf or f undef. while near pt.
End behavior: ratio of leading coeffs (rational); dom. term (poly/exp). Increasing: f' > 0; decreasing: f' < 0.
Graph interpretation: f' tells slope, f'' tells concavity. On FRQ, always state f' = 0 & verify with 2nd test.

Table with 2 columns: Analysis, Check. Rows include Max/min, Inflection, Concav. up/down, Vert. asym.

FRQ Strategy

Always interpret f', f'' in context: "rate of change of...", "accel of...".
Optimization: show f' = 0, verify with 2nd deriv. test, state answer w/ units.
Related rates: sketch -> label vars -> diff. wrt time -> substitute -> solve.

Integration Techniques (Unit 6)

Core Antiderivatives & Rules
Power: integral x^n dx = x^(n+1)/(n+1) + C (n != -1). Exp: integral e^x dx = e^x + C.
1/x: integral 1/x dx = ln|x| + C.
Trig: integral sin x dx = -cos x + C; integral cos x dx = sin x + C; integral sec^2 x dx = tan x + C.
u-sub: choose u = inner fn., du = u' dx, rewrite integral in u, integrate, back-sub. Check: u' divides integrand.
Integration by Parts & Fractions

By parts: integral u dv = uv - integral v du. LIATE: ln, inv. trig, alg., trig, exp. (pick u by priority). Useful for uv, x*e^x, x*ln x.
Partial fractions: decompose rational fn. into sum of simpler fractions. Steps: factor denom., set up form, solve for coeff., integrate each term.

Improper integrals: integral_a^inf f(x) dx = lim_{t-to+inf} integral_a^t f(x) dx. Converges if limit is finite. Also handle at x = c where f(c) undef.

Accumulation & Area

FTC I: integral_a^b f(x) dx = F(b) - F(a) (F' = f).
FTC II: integral_a^b f(x) dx = F(b) - F(a) (F' = f).
Net area: integral_a^b f(x) dx = area above - area below x-axis.
Total area: integral_a^b |f(x)| dx.
Riemann sums: Left/right/mid approximate f with rectangles. Trap. rule: (b-a)/n * [f(x_0)/2 + f(x_1) + ... + f(x_n)/2].
Acc. fns: F(x) = integral_a^x f(t) dt. F'(x) = f(x); F''(x) = f'(x). Use to define & evaluate antiderivatives.

Table with 2 columns: u-Sub Type, Example. Rows include Power inside, Exp/ln, Trig in chain.

+C on indefinite. Improper: watch for discontinuities in [a,b].

u-sub: if u' doesn't divide integrand cleanly, wrong u choice.

Differential Equations & Integration Apps (Units 7-8)

Separable DEs & Slope Fields
Separable: dy/dx = f(x)g(y). Separate: g(y) dy = f(x) dx. Integrate both sides, solve for y.
Slope field: plot (x,y) & direction dy/dx. Solutions follow field. Use: match DE to field by checking slopes.
Euler's method: y_{n+1} = y_n + Delta y; Delta y = f(x_n, y_n) * h (h = step size). Approximate solution via iterations.

Growth Models

Exponential: dy/dt = ky. Solution: y(t) = y_0 e^{kt}. Half-life: t = (ln 2)/k. Double time: t = (ln 2)/k.
Logistic: dy/dt = ky(L-y)/L (L = carrying capacity). Solution: y(t) = L / (1 + Ae^{-kt}). Approaches L asymptotically.
Linear DE: dy/dt + P(t)y = Q(t). Integrating factor: e^{integral P(t) dt}. Multiply by integrating factor, integrate.

Volumes & Solids

Disk method: V = integral_a^b pi[R(x)]^2 dx. Washer: V = integral_a^b pi([R(x)]^2 - [r(x)]^2) dx.
Shell method: V = 2pi integral_a^b (radius)(height) dx = 2pi integral_a^b f(x) dx (rotate around y-axis).
Arc length: L = integral_a^b sqrt(1 + (dy/dx)^2) dx.
Surface area: S = 2pi integral_a^b y sqrt(1 + (dy/dx)^2) dx.
Work: W = integral_a^b F(x) dx.
Avg. value: f_avg = 1/(b-a) * integral_a^b f(x) dx.
Mean Value Thm for Integrals: exists c where f(c) = f_avg.

Table with 2 columns: Method, Formula. Rows include Disk, Washer, Shell, Arc len.

Always sketch region, label R(x)/r(x), set up bounds. Rotate -> disk; along side -> shell.

Arc len hard to integrate; often leave in integral form or use approx/calc.

Parametric Equations & Vector Functions (Unit 9 Part 1)

Parametric Curves

Parametric: x = f(t), y = g(t) trace curve as t varies. dy/dx = (dy/dt) / (dx/dt). d^2y/dx^2 = d/dx(dy/dx).
Eliminate parameter: solve one eq. for t, substitute into other. Use if curve has simple form (ellipse, line).
Velocity: (dx/dt, dy/dt). Speed: || = sqrt((dx/dt)^2 + (dy/dt)^2).
Acceleration: = (d^2x/dt^2, d^2y/dt^2).
Arc length (param): L = integral_a^b sqrt((dx/dt)^2 + (dy/dt)^2) dt.
Area under curve: A = integral_a^b y(t) * x'(t) dt.

Vector-Valued Functions

Vector fn.: r(t) = . Derivative: r'(t) = . Integral: integral r(t) dt = < integral f(t) dt, integral g(t) dt >.
Magnitude: ||r(t)|| = sqrt(f(t)^2 + g(t)^2). Dot product: u . v = u_1v_1 + u_2v_2. Orthogonal: u . v = 0.
Unit tangent: T(t) = r'(t) / ||r'(t)||. Normal accel.: a_N = |a . N|. Tangent accel.: a_T = (v . a) / |v|.
Projectile motion: x(t) = x_0 + v_0x t; y(t) = y_0 + v_0y t - (1/2)gt^2. Solve y = 0 for landing time.
Position fn.: r(t) satisfies r'(t) = velocity, r''(t) = acceleration. Initial conditions: r(0), r'(0).

Table with 2 columns: Concept, Formula. Rows include Speed, Arc len, Unit tangent, Dot prod.

2nd deriv. of param: d^2y/dx^2 = d/dt(dy/dx) / (dx/dt).
Concavity: >0 -> concave up; <0 -> concave down.

Param arc len easy to set up, hard to integrate. On MC: use calc or approx.
Speed vs. velocity: speed is magnitude (scalar); velocity is vector w/ direction.

Polar Coordinates & Curves (Unit 9 Part 2)

Polar to Cartesian

Polar form: (r, theta) where x = r cos theta, y = r sin theta. Inverse: r = sqrt(x^2 + y^2), theta = arctan(y/x) [adjust quadrant].
Polar curve: r = f(theta). Trace as theta varies. dy/dx = (r' sin theta + r cos theta) / (r' cos theta - r sin theta) where r' = dr/dtheta.
Tangent line at theta: use formula above or convert to parametric x = r cos theta, y = r sin theta, find dy/dx.
Horizontal tangent: dy/dtheta = 0 (not dy/dx). Vertical tangent: dx/dtheta = 0. Tangent passes origin: r = 0.

Area & Arc Length

Polar area: A = (1/2) integral_a^b r^2 dtheta. Setup: sketch region, identify theta bounds, set up integral.
Area b/w curves: A = (1/2) integral_a^b (r_1^2 - r_2^2) dtheta. Assume r_1 > r_2 in region.
Polar arc length: L = integral_a^b sqrt(r^2 + (dr/dtheta)^2) dtheta. Use: only if integrable; else approx. or leave answer.

Common Polar Curves

Circle: r = a (center origin); spiral: r = a theta; rose: r = a sin(n theta) or a cos(n theta).
Limaçon: r = a +/- b cos theta; cardioid: r = a(1 +/- cos theta) [loop if inner]; lemniscate: r^2 = a^2 cos 2 theta.

Table with 2 columns: Curve, Petals/Shape. Rows include r=a sin n theta, r=a cos n theta, r=a(1+cos theta), r^2=a^2 cos 2 theta, r=a theta.

Polar area has (1/2) factor! A = (1/2) integral r^2 dtheta, not integral r^2 dtheta.

Check: does r = 0 in [alpha, beta]? If yes, region includes origin. Sketch!

Sequences & Series Fundamentals (Unit 10 Pt. 1)

Sequences & Limits

Sequence: ordered list {a_n}. Limit: lim_{n-to+inf} a_n = L iff given epsilon > 0, exists N where |a_n - L| < epsilon for n > N.
Convergent: limit exists (finite). Divergent: limit = +/-inf or oscillates. Monotonic: up or down; bounded: |a_n| <= M.
Monotonic + bounded = convergent. Find limit: evaluate lim_{n-to+inf} (use L-Hopital on indeterminate forms).

Infinite Series Basics

Series: Sigma a_n = a_1 + a_2 + ... Partial sum: S_N = Sigma_{n=1}^N a_n.
Series conv. iff {S_N} converges.
Geometric: Sigma ar^{n-1} = a/(1-r) if |r| < 1.
p-series: Sigma 1/n^p conv. iff p > 1.
Divergence test: if lim a_n != 0, series diverges. If lim a_n = 0, test is inconclusive (need convergence test).
Telescoping: (b_n - b_{n+1}). Partial sums collapse: S_N = b_1 - b_{N+1}. Take lim as N -> inf.

Series Convergence Tests

Integral test: Sigma a_n = integral_a^inf f(x) dx (both conv. or both div.). f must be pos., cont., decr.
Comparison: if 0 <= a_n <= b_n & Sigma b_n conv., then Sigma a_n conv.
Limit comparison: lim (a_n/b_n) > 0 & finite.
Ratio test: lim |a_{n+1}/a_n| = L. L < 1 -> conv.; L > 1 -> div.; L = 1 -> inconclusive.
Root test: lim |a_n|^{1/n} = L. L < 1 -> conv.; L > 1 -> div.; L = 1 -> inconclusive.
Alternating series: Sigma (-1)^n a_n conv. if a_n down to 0 & lim a_n = 0 (AST). Absolute: Sigma |a_n| conv. => Sigma a_n conv.

Table with 2 columns: Test, Condition. Rows include p-series, Integral, Ratio, Root, Alt. series.

Always check divergence test FIRST (easiest)

Convergence Tests & Power Series + FRQ (Unit 10 Part 2)

Power Series & Taylor

Power series: Sigma c_n(x-a)^n. Radius of conv. R from ratio test: |x-a| < R. Interval: (a-R, a+R); test endpoints.
Taylor at x=a: f(x) = Sigma f^{(n)}(a)/n! * (x-a)^n. Maclaurin (a=0): f(x) = Sigma f^{(n)}(0)/n! * x^n.
Key series: e^x = Sigma x^n/n!; sin x = Sigma (-1)^n x^{2n+1}/(2n+1)!; cos x = Sigma (-1)^n x^{2n}/(2n)!.
Geometric: 1/(1-x) = Sigma x^n (|x| < 1); ln(1+x) = Sigma (-1)^{n+1} x^n/n (-1 < x <= 1).

Error Bounds & Lagrange

Lagrange error: |R_n(x)| <= M/(n+1)! * |x-a|^{n+1} where |f^{(n+1)}(c)| <= M on interval.
Alternating series error: |error| <= |first omitted term|. Use to bound approximation error or find n.

Operations on Series

Diff./integrate power series term-by-term (within radius). Derive sin x from cos x via integration.
Substitution: replace x in known series. E.g. e^{2x} from e^x: Sigma (2x)^n/n! = Sigma 2^n x^n/n!.
Mult./div. series (rare on BC): multiply out, collect like terms.

FRQ Series & Calc Strategies

Series Q: name test, state conditions, show work (lim, ratio, integral). State convergence clearly.
Radius/interval: use ratio test, find R, test endpoints separately (AST? p-series?).
Power series: recognize fn., write series from memory or derive, substitute, integrate/diff. if needed.
Taylor error: bound with Lagrange; alt. series: omitted term. Never just guess magnitude.
Calc: know when allowed (Part B MC, Part A FRQ). Use to verify answers, solve transcendental eqs.